



Robust Deep Metric Learning for Remote Sensing Images with Label Noise

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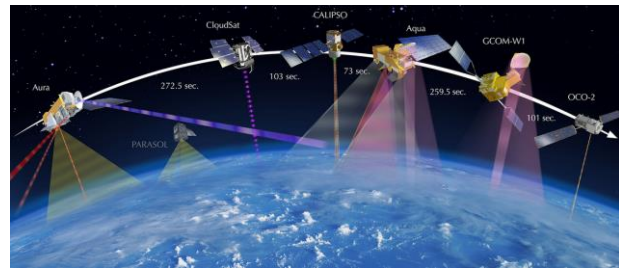


Outline

- Introduction
- Motivation
- Background Knowledge
- Robust Normalized Softmax Loss (RNSL)
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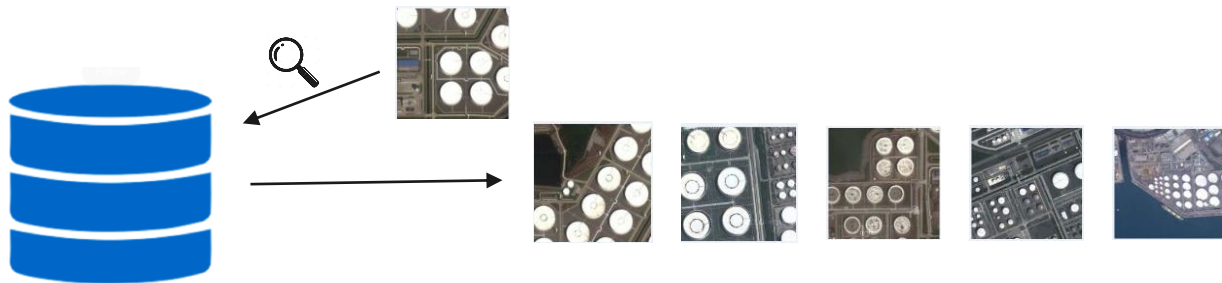
Introduction

- Remote Sensing (RS) technology development meets big Earth Observation (EO) data



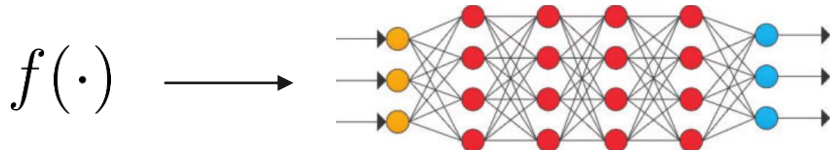
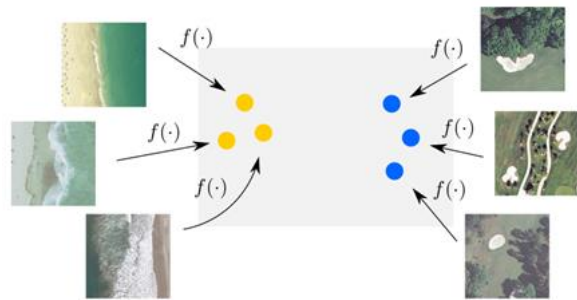
Credit: Wikipedia

- Retrieving interested contexts from big EO data is a basic task in RS



Introduction

- Characterizing the contexts of RS images with low-dimensional features is the key for achieving image retrieval
- Deep learning has been a workhorse for learning those features



Introduction

- Labeling RS scene datasets for developing advanced deep metric learning algorithms

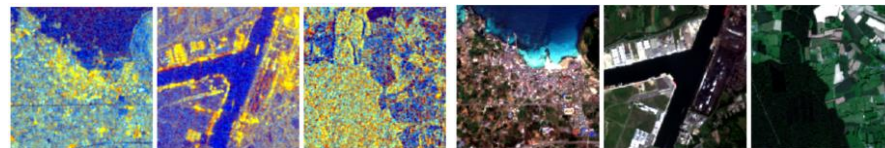
- Human experts: AID^[1] , NWPU-RESISC45^[2]

AID:



- Crowd-sourcing data: SEN12MS^[3]

SEN12MS:



[1] Xia, Gui-Song, et al. "AID: A benchmark data set for performance evaluation of aerial scene classification." *IEEE Transactions on Geoscience and Remote Sensing* 55.7 (2017): 3965-3981.

[2] Cheng, Gong, Junwei Han, and Xiaoqiang Lu. "Remote sensing image scene classification: Benchmark and state of the art." *Proceedings of the IEEE* 105.10 (2017): 1865-1883.

[3] Schmitt, Michael, et al. "SEN12MS--A Curated Dataset of Georeferenced Multi-Spectral Sentinel-1/2 Imagery for Deep Learning and Data Fusion." *arXiv preprint arXiv:1906.07789* (2019).

Introduction

- Labeling based on crowd-sourcing data may contain noise
 - geo-location/registration errors
 - land-cover changes
 - low-quality Volunteered Geographic Information (VGI)



Bare land → Desert



Church → Downtown



Farmland → Meadow

Motivation and Background Knowledge

- Extracting deep embeddings of RS images in a robust manner

- Noise type:

- Uniform noise:
a true label is flipped into other labels with equal probability
- Label-dependent noise:
a true label is more likely to be mistakenly labeled with a particular class

uniform noise



farmland

↓
bareland, forest, port, church...

label-dependent noise



farmland

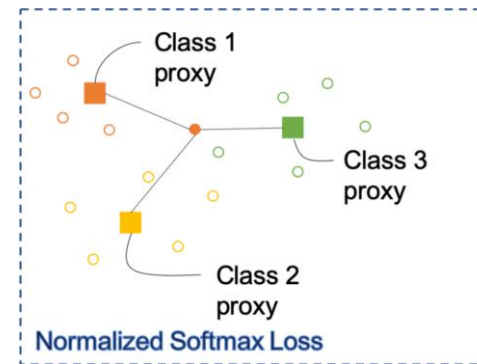
↓
forest

Background Knowledge

- Normalized Softmax Loss (NLS) [5]

$$L_{\text{NSL}} = -\frac{1}{N} \sum_i \sum_c y_i^c \log \left(\frac{\exp(\mathbf{w}_c^T f(\mathbf{x}_i)/\sigma)}{\sum_k \exp(\mathbf{w}_k^T f(\mathbf{x}_i)/\sigma)} \right)$$

- Objectives of NLS:
 - Learning the normalized center embedding for each class
 - Pulling the features of each class to their associated center embeddings in latent space



Credit: [5]

Robust Normalized Softmax Loss (RNSL)

- Gradients of L_{RNSL} with respect to \mathbf{w}_c :

$$\frac{\partial L_{\text{RNSL}}}{\partial \mathbf{w}_c} = -\frac{1}{N} \sum_i \sum_c \frac{y_i^c}{p_i^c} \frac{\partial p_i^c}{\partial \mathbf{w}_c}$$

$$\text{Classification probability } p_i^c = \frac{\exp(\mathbf{w}_c^T f(\mathbf{x}_i)/\sigma)}{\sum_k \exp(\mathbf{w}_k^T f(\mathbf{x}_i)/\sigma)}$$

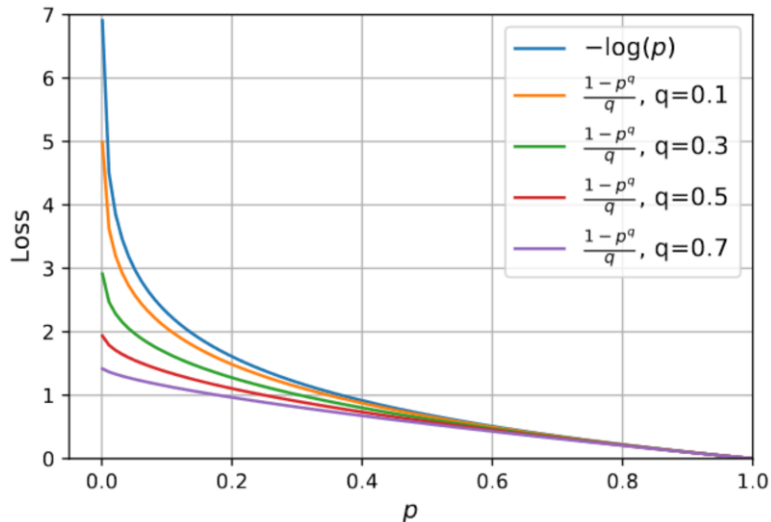
- Hard samples are given more attention than the ones which are easily classified**
- When label noise exists, L_{RNSL} can lead the trained models overfitting to noisy samples**

Robust Normalized Softmax Loss (RNSL)

- RNSL exploits negative Box-Cox transformation with the form [6,7]:

$$L_{\text{RNSL}} = \frac{1}{N} \sum_i \sum_c y_i^c \frac{(1 - (p_i^c)^q)}{q}, \quad q \in (0, 1)$$

- With different values of q , the loss changes with respect to the classification probability p



[6] Zhang, Zhilu, and Mert R. Sabuncu. "Generalized cross entropy loss for training deep neural networks with noisy labels." arXiv preprint arXiv:1805.07836 (2018).

[7] Kang, Jian, et al. "Robust Normalized Softmax Loss for Deep Metric Learning-Based Characterization of Remote Sensing Images With Label Noise." IEEE Transactions on Geoscience and Remote Sensing (2020).

Robust Normalized Softmax Loss (RNSL)

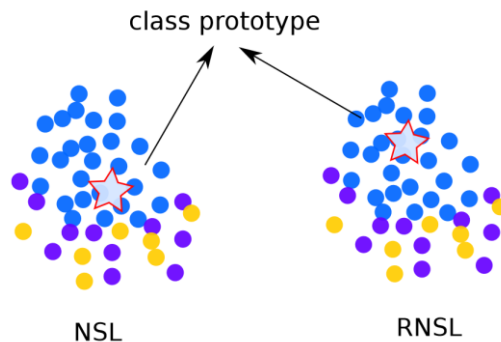
- Gradients of L_{RNSL} with respect to \mathbf{W}_c :

$$\frac{\partial L_{\text{RNSL}}}{\partial \mathbf{w}_c} = \frac{1}{N} \sum_i \sum_c y_i^c (p_i^c)^q \left(-\frac{1}{p_i^c} \frac{\partial p_i^c}{\partial \mathbf{w}_c} \right)$$

$$\frac{\partial L_{\text{NSL}}}{\partial \mathbf{w}_c} = -\frac{1}{N} \sum_i \sum_c \frac{y_i^c}{p_i^c} \frac{\partial p_i^c}{\partial \mathbf{w}_c}$$

- Downweighting effects of $(p_i^c)^q$, which can reduce the influence of noisy samples on learning the parameters

$$\lim_{q \rightarrow 0} L_{\text{RNSL}} = L_{\text{NSL}}$$





Robust Normalized Softmax Loss (RNSL)

- To further improve the robustness of RNSL when have noisy labels exist, a truncated version of RNSL is introduced:

$$\mathcal{L}_{t-RNSL} = \frac{1}{N} \sum_i \sum_c y_i^c \begin{cases} \frac{1-k^q}{q}, & \text{if } p_i^c \leq k \\ \frac{1-(p_i^c)^q}{q}, & \text{if } p_i^c > k \end{cases}$$

- The training strategy:
 - Within the first T epochs, the models are trained with RNSL
 - After T epochs, the loss function is switched to the truncated version



Experimental Setup

Dataset	AID; NWPU-RESISC45
Noise Type	Uniform; Label-dependent
Noise Level	0.1; 0.3; 0.5; 0.7
Data Splitting	Train:0.7, Val:0.1, Test:0.2
Tasks	KNN classification; Clustering; Image retrieval
Metrics	OA; NMI; ACC; MAP



Experimental Setup

- Compared methods:
 - D-CNN^[8]
 - Triplet^[9]
 - SNCA^[10]
 - NSL^[5]
 - ArcFace^[11]

[8] Cheng, Gong, et al. "When deep learning meets metric learning: Remote sensing image scene classification via learning discriminative CNNs." *IEEE transactions on geoscience and remote sensing* 56.5 (2018): 2811-2821.

[9] Schroff, Florian, Dmitry Kalenichenko, and James Philbin. "Facenet: A unified embedding for face recognition and clustering." *Proceedings of the IEEE conference on computer vision and pattern recognition*. 2015.

[10] Wu, Zhirong, Alexei A. Efros, and Stella X. Yu. "Improving generalization via scalable neighborhood component analysis." *Proceedings of the European Conference on Computer Vision (ECCV)*. 2018.

[5] Zhai, Andrew, and Hao-Yu Wu. "Classification is a strong baseline for deep metric learning." *arXiv preprint arXiv:1811.12649* (2018).

[11] Deng, Jiankang, et al. "Arcface: Additive angular margin loss for deep face recognition." *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*. 2019.

Experimental Results

- KNN classification

	AID								NWPU-RESISC45							
	Uniform				Label-dependent				Uniform				Label-dependent			
	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7
D-CNN	92.40	86.80	75.25	60.10	92.45	88.95	84.40	84.25	90.05	81.92	88.62	40.59	90.06	85.70	80.00	77.19
Triplet	91.80	85.35	77.15	55.35	93.30	90.50	85.80	85.60	86.92	75.19	61.57	50.68	90.06	87.76	83.41	79.25
NSL	89.35	84.35	75.60	63.90	90.20	87.25	85.15	84.15	87.46	78.73	65.57	45.38	88.27	84.14	80.19	78.00
SNCA	90.65	82.70	64.55	42.90	90.40	81.95	75.40	74.45	87.90	76.08	59.75	30.03	87.17	77.97	68.02	63.44
ArcFace	90.30	79.95	87.30	82.30	90.80	81.35	86.55	83.60	87.75	88.68	85.52	80.71	87.16	71.25	80.35	78.25
MAE	82.15	82.70	79.90	80.65	83.45	81.05	82.25	81.15	78.69	78.53	75.43	74.03	77.94	77.65	76.97	77.17
RNSL	93.25	91.15	81.10	54.25	93.15	85.65	79.65	76.10	92.25	88.92	80.54	49.63	91.30	84.32	74.35	68.21
t-RNSL	94.05	91.80	89.50	78.25	93.80	90.50	86.05	81.55	92.30	90.76	88.56	79.84	92.03	89.30	84.84	76.84

Experimental Results

- Clustering
 - ACC

	AID								NWPU-RESISC45							
	Uniform				Label-dependent				Uniform				Label-dependent			
	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7
D-CNN	91.65	80.90	65.50	28.85	87.70	79.50	73.35	64.50	86.86	77.86	85.00	17.41	85.71	78.65	66.40	59.78
Triplet	89.20	79.40	65.25	34.20	89.70	85.20	70.95	65.30	79.21	60.40	42.54	25.30	84.41	80.94	72.60	57.54
NSL	85.10	71.85	45.30	21.75	87.25	77.95	70.70	68.55	80.97	69.41	43.81	10.75	83.19	74.95	69.35	65.65
SNCA	90.00	81.75	60.20	26.30	90.15	79.05	63.80	59.55	88.00	76.06	58.59	24.62	86.94	76.21	60.03	47.02
ArcFace	90.55	79.25	78.50	68.95	87.90	77.00	65.30	62.00	87.70	78.48	75.41	68.38	86.87	68.49	52.73	48.62
MAE	63.85	66.45	53.30	57.75	67.15	57.20	56.45	56.65	52.13	52.97	50.70	46.46	53.33	50.13	51.84	49.37
RNSL	90.90	90.45	72.60	23.75	90.70	76.75	62.90	54.85	89.41	88.11	75.59	26.86	88.33	79.68	64.14	53.41
t-RNSL	94.00	91.40	86.60	69.55	93.50	86.65	76.55	63.20	91.48	90.27	84.98	78.16	89.22	86.63	75.10	61.22

Experimental Results

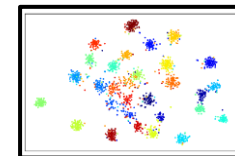
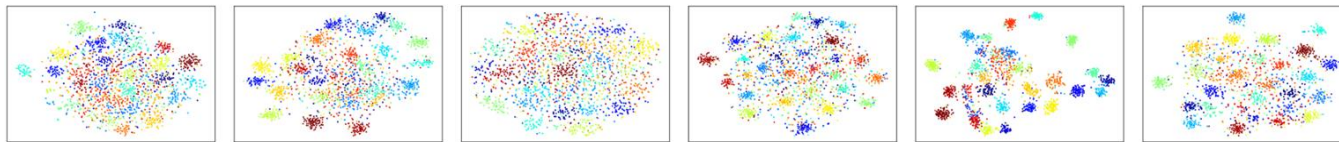
- Image Retrieval
 - MAP@20

	AID								NWPU-RESISC45							
	Uniform				Label-dependent				Uniform				Label-dependent			
	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7	0.1	0.3	0.5	0.7
D-CNN	93.25	84.63	69.17	50.98	93.44	87.28	81.46	78.61	91.60	80.94	90.28	41.53	91.02	85.24	77.80	73.44
Triplet	93.13	85.87	74.96	56.34	93.79	90.64	86.44	83.56	87.99	75.10	61.50	51.79	90.95	89.57	84.42	78.85
NSL	90.61	81.01	67.96	55.26	90.40	85.50	81.84	78.96	88.71	76.53	62.30	44.44	89.39	83.42	78.14	75.52
SNCA	96.81	89.12	68.92	48.05	95.41	85.72	78.64	76.99	96.09	85.49	67.07	42.06	92.71	83.24	72.64	69.38
ArcFace	96.04	85.55	85.41	77.27	94.72	83.88	84.47	81.73	96.17	88.59	85.20	78.30	93.84	77.83	79.69	77.37
MAE	79.18	80.09	74.04	74.77	81.88	76.29	77.04	76.27	76.03	75.57	73.13	69.74	81.88	76.29	77.04	76.27
RNSL	95.53	93.28	82.23	51.48	94.78	85.72	76.92	71.12	95.26	92.43	84.49	53.21	94.11	86.24	73.25	66.62
t-RNSL	96.04	93.71	90.55	77.41	95.38	91.37	86.53	77.79	95.10	94.11	91.33	83.29	94.83	91.32	85.35	76.23

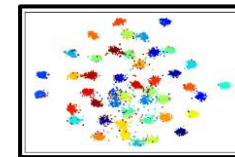
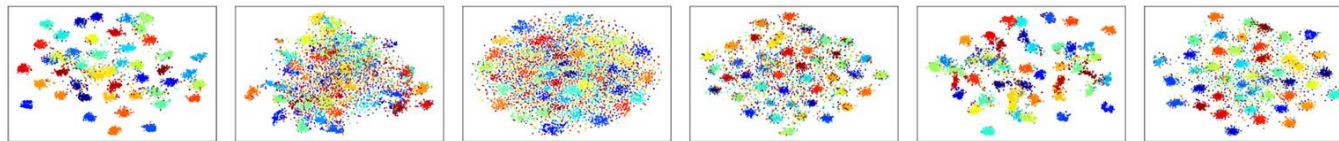
Experimental Results

- Feature visualization (noise level:0.5)
 - t-SNE

AID



NWPU-RESISC45





Conclusion

- A novel robust loss function is proposed for deep embedding of RS images
- Compared to other state-of-the-art methods, RNSL achieves significant performance improvement in several tasks when the noisy labels exist



Thank you for your attention!



<https://jiankang1991.github.io/>